

favorable or the cycle length is very short. If it is due to favorable progression, most vehicles arrive during the green indication and travel through the intersection without stopping.

LOS B describes operations with control delay between 10 and 20 s/veh and a volume-to-capacity ratio no greater than 1.0. This level is typically assigned when the volume-to-capacity ratio is low and either progression is highly favorable or the cycle length is short. More vehicles stop than with LOS A.

LOS C describes operations with control delay between 20 and 35 s/veh and a volume-to-capacity ratio no greater than 1.0. This level is typically assigned when progression is favorable or the cycle length is moderate. Individual *cycle failures* (i.e., one or more queued vehicles are not able to depart as a result of insufficient capacity during the cycle) may begin to appear at this level. The number of vehicles stopping is significant, although many vehicles still pass through the intersection without stopping.

LOS D describes operations with control delay between 35 and 55 s/veh and a volume-to-capacity ratio no greater than 1.0. This level is typically assigned when the volume-to-capacity ratio is high and either progression is ineffective or the cycle length is long. Many vehicles stop and individual cycle failures are noticeable.

LOS E describes operations with control delay between 55 and 80 s/veh and a volume-to-capacity ratio no greater than 1.0. This level is typically assigned when the volume-to-capacity ratio is high, progression is unfavorable, and the cycle length is long. Individual cycle failures are frequent.

LOS F describes operations with control delay exceeding 80 s/veh or a volume-to-capacity ratio greater than 1.0. This level is typically assigned when the volume-to-capacity ratio is very high, progression is very poor, and the cycle length is long. Most cycles fail to clear the queue.

A lane group can incur a delay less than 80 s/veh when the volume-to-capacity ratio exceeds 1.0. This condition typically occurs when the cycle length is short, the signal progression is favorable, or both. As a result, both the delay and volume-to-capacity ratio are considered when lane group LOS is established. A ratio of 1.0 or more indicates that cycle capacity is fully utilized and represents failure from a capacity perspective (just as delay in excess of 80 s/veh represents failure from a delay perspective).

Exhibit 18-4 lists the LOS thresholds established for the automobile mode at a signalized intersection.

Exhibit 18-4
LOS Criteria: Automobile
Mode

Control Delay (s/veh)	LOS by Volume-to-Capacity Ratio ^a	
	≤1.0	>1.0
≤10	A	F
>10–20	B	F
>20–35	C	F
>35–55	D	F
>55–80	E	F
>80	F	F

Note: ^a For approach-based and intersectionwide assessments, LOS is defined solely by control delay.

Exhibit 19-1
Level-of-Service Criteria:
Automobile Mode

Control Delay (s/vehicle)	LOS by Volume-to-Capacity Ratio	
	$v/c \leq 1.0$	$v/c > 1.0$
0–10	A	F
>10–15	B	F
>15–25	C	F
>25–35	D	F
>35–50	E	F
>50	F	F

Note: The LOS criteria apply to each lane on a given approach and to each approach on the minor street. LOS is not calculated for major-street approaches or for the intersection as a whole.

Pedestrian LOS at TWSC intersections is defined for pedestrians crossing a traffic stream not controlled by a STOP sign; it also applies to midblock pedestrian crossings. LOS criteria for pedestrians are given in Exhibit 19-2.

Exhibit 19-2
Level-of-Service Criteria:
Pedestrian Mode

LOS	Control Delay (s/pedestrian)	Comments
A	0–5	Usually no conflicting traffic
B	5–10	Occasionally some delay due to conflicting traffic
C	10–20	Delay noticeable to pedestrians, but not inconveniencing
D	20–30	Delay noticeable and irritating, increased likelihood of risk taking
E	30–45	Delay approaches tolerance level, risk-taking behavior likely
F	>45	Delay exceeds tolerance level, high likelihood of pedestrian risk taking

Note: Control delay may be interpreted as s/pedestrian group if groups of pedestrians were counted as opposed to individual pedestrians.

LOS F for pedestrians occurs when there are not enough gaps of suitable size to allow waiting pedestrians to cross through traffic on the major street safely. This situation is typically evident from extremely long control delays. The method is based on a constant critical headway. In the field, however, LOS F may also appear in the form of crossing pedestrians selecting smaller-than-usual gaps. In such cases, safety could be a concern that warrants further study.

REQUIRED INPUT DATA

Analysis of a TWSC intersection requires the following data:

1. Number and configuration of lanes on each approach;
2. Percentage of heavy vehicles for each movement;
3. Either of the following:
 - a. Demand flow rate for each entering vehicular movement and each pedestrian crossing movement during the peak 15 min, or
 - b. Demand flow rate for each entering vehicular movement and each pedestrian crossing movement during the peak hour and a peak hour factor for the hour;
4. Special geometric factors such as
 - a. Unique channelization aspects,
 - b. Existence of a two-way left-turn lane or raised or striped median storage (or both),

Control Delay (s/veh)	LOS by Volume-to-Capacity Ratio*	
	$v/c \leq 1.0$	$v/c > 1.0$
0–10	A	F
>10–15	B	F
>15–25	C	F
>25–35	D	F
>35–50	E	F
>50	F	F

Note: * For approaches and intersectionwide assessment, LOS is defined solely by control delay.

Exhibit 20-2

LOS Criteria: Automobile Mode

REQUIRED INPUT DATA

Analysis of an AWSC intersection requires the following data:

1. Number and configuration of lanes on each approach;
2. Percentage of heavy vehicles;
3. Turning movement demand flow rate for each entering lane or, alternatively, hourly demand volume and peak hour factor; and
4. Length of analysis period—generally a peak 15-min period within the peak hour, although any 15-min period can be analyzed.

SCOPE OF THE METHODOLOGY

This chapter focuses on the operation of AWSC intersections. This version of the AWSC intersection analysis procedures is primarily a result of studies conducted by National Cooperative Highway Research Program Project 3-46 (1).

LIMITATIONS OF THE METHODOLOGY**Automobile Mode**

The methodologies in this chapter apply to isolated AWSC intersections with up to three lanes on each approach. They do not account for interaction effects with other intersections. The methodologies do not apply to AWSC intersections with more than four approaches. In addition, the effect of conflicting pedestrians on automobiles is not considered in this procedure. Conflicting pedestrian movements are likely to increase the saturation headway of affected vehicular movements, but the magnitude of this effect is unknown as of the publication of this edition of the HCM.

Pedestrian and Bicycle Modes

The current methodologies for analyzing LOS and delay at AWSC intersections do not extend to pedestrians and apply to bicycles only in limited situations that are not supported by research at the time of publication of this edition. As such, there are no set LOS standards that apply to pedestrians or bicycles at AWSC intersections, nor can pedestrian or bicycle delay, capacity, or quality of service be quantitatively assessed by using the procedures described in this chapter. Additional research on pedestrian and bicyclist behavior and operations at AWSC intersections needs to be done before procedures can be developed that adequately address these issues. A discussion of qualitative effects is included in the methodology section of this chapter.

LOS A–E is defined in terms of density; LOS F exists when demand exceeds capacity.

- No heavy vehicles,
- 12-ft lanes,
- Adequate lateral clearances (≥ 6 ft), and
- Road users familiar with the facility (i.e., $f_p = 1.00$).

LOS CRITERIA FOR MERGE AND DIVERGE SEGMENTS

Merge/diverge segment LOS is defined in terms of density for all cases of stable operation (LOS A–E). LOS F exists when the freeway demand exceeds the capacity of the upstream (diverges) or downstream (merges) freeway segment, or where the off-ramp demand exceeds the off-ramp capacity.

At LOS A, unrestricted operations exist, and the density is low enough to permit smooth merging or diverging with very little turbulence in the traffic stream. At LOS B, merging and diverging maneuvers become noticeable to through drivers, and minimal turbulence occurs. At LOS C, speed within the ramp influence area begins to decline as turbulence levels become much more noticeable. Both ramp and freeway vehicles begin to adjust their speeds to accomplish smooth transitions. At LOS D, turbulence levels in the influence area become intrusive, and virtually all vehicles slow to accommodate merging or diverging maneuvers. Some ramp queues may form at heavily used on-ramps, but freeway operation remains stable. LOS E represents operating conditions approaching or at capacity. Small changes in demand or disruptions within the traffic stream can cause both ramp and freeway queues to form.

LOS F defines operating conditions within queues that form on both the ramp and the freeway mainline when capacity is exceeded by demand. For on-ramps, LOS F exists when the total demand flow rate from the upstream freeway segment and the on-ramp exceeds the capacity of the downstream freeway segment. For off-ramps, LOS F exists when the total demand flow rate on the approaching upstream freeway segment exceeds the capacity of the upstream freeway segment. LOS F also occurs when the off-ramp demand exceeds the capacity of the off-ramp.

Exhibit 13-2 summarizes the LOS criteria for freeway merge and diverge segments. These criteria apply to all ramp–freeway junctions and may also be applied to major merges and diverges; high-speed, uncontrolled merge or diverge ramps on multilane highway sections; and merges and diverges on freeway C-D roadways. LOS is not defined for ramp roadways, while the LOS of a ramp–street junction is defined in Chapter 22, Interchange Ramp Terminals.

Exhibit 13-2
LOS Criteria for Freeway
Merge and Diverge
Segments

LOS	Density (pc/mi/ln)	Comments
A	≤ 10	Unrestricted operations
B	$>10-20$	Merging and diverging maneuvers noticeable to drivers
C	$>20-28$	Influence area speeds begin to decline
D	$>28-35$	Influence area turbulence becomes intrusive
E	>35	Turbulence felt by virtually all drivers
F	Demand exceeds capacity	Ramp and freeway queues form